Learning to Follow Navigational Directions Adam Vogel and Dan Jurafsky Stanford University

Learning by Apprenticeship

Problem: Without linguistic annotation:

•Can we learn the meaning of spatial words like *left* and *down*? •Can we learn to interpret textual directions on a map?

Traditional approaches to semantic interpretation are insufficient: •Supervised approaches use expensive hand-labeled semantic annotation.

 Unsupervised approaches that learn semantics only from word distributions can't deal with spatial terms.

Our solution: Induce the meaning of spatial language from natural language route descriptions paired with a path on a map, using reinforcement learning.



Map Task

• Two people have a map with named landmarks

 The instruction giver describes a path on the map

The **instruction follower** draws the path described

 Our system learns to be the instruction follower

Reinforcement Learning

Find θ which best models expected reward of choosing an action:

$Q(s,a) = \theta \cdot \phi(s,a)$

Learning Algorithm: SARSA, an approximation to value iteration

Features φ(s,a)

- Is the target landmark is closest?
- Is this the closest side of the landmark?
- Is this the null action?

• How many words in the name of the target landmark occur in the utterance?

• Allocentric spatial features: A feature combining each spatial word in the utterance with the side we pass the landmark on. These features capture landmark-centric spatial relations.

Ex: *right* appears and we pass to the south of the landmark • Egocentric spatial features: A feature for every spatial word in the utterance conjoined with the cardinal direction we move in. These capture agent-centric spatial relations.

Ex: *right* appears and we move to the east

above, below, under, underneath, over, bottom, top, up, down, left, right, north, south, east, west, on

